RESEARCH CENTER
Lille - Nord Europe

FIELD

Activity Report 2019

Section Software

Edition: 2020-03-21

6. New Software and Platforms

6.1. Platforms

6.1.1. Grid'5000 testbed: extension with storage and 10G network at Lille

Participants: Nouredine Melab [contact person], Dimitri Delabroye, Thierry Peltier [external collaborator], Lucas Nussbaum [external collaborator].

Keywords: Experimental testbed, large-scale computing, high-performance computing, GPU computing, cloud computing, big data

Functional description: Grid'5000 is a project intiated in 2003 by the French government to promote scientific research on large scale distributed systems. The project is later supported by different research organizations including Inria, CNRS, the french universities, Renater which provides the wide-area network etc. The overall objective of Grid'5000 was to build by 2007 a nation-wide experimental testbed composed of at least 5000 processing units and distributed over several sites in France. From a scientific point of view, the aim was to promote scientific research on large-scale distributed systems.

Grid'5000 was installed at the center of IT resources including supercomputing resources of Université de Lille 1 and opened to users in 2005. Since March 2017, the Grid'5000 site has moved to the premises on Inria Lille within the context of the phase 1 of the CPER data program (see Section 9.1) with a completely new hardware equipement. As a scientific leader of the testbed for the Lille's site, N. Melab has been strongly involved in the extension (phase 2 of CPER data) of the platform with mainly two storage serveurs 200TB and a 10G Internet connexion to the testbed. Grid'5000 at Lille is used by more than 150 users including 100 external ones. The testbed is used for research as well as for teaching allowing a high scientific production (publications, PhD theses etc.) and over 30 master students to get started with parallel and distributed programming.

URL: https://www.grid5000.fr/mediawiki/index.php/Grid5000:Home

<p style="text-align: center; color: red;">**DEFROST Project-Team**</p>

6. New Software and Platforms

6.1. SOFA

Simulation Open Framework Architecture

KEYWORDS: Real time - Multi-physics simulation - Medical applications

FUNCTIONAL DESCRIPTION: SOFA is an Open Source framework primarily targeted at real-time simulation, with an emphasis on medical simulation. It is mostly intended for the research community to help develop new algorithms, but can also be used as an efficient prototyping tool. Based on an advanced software architecture, it allows : the creation of complex and evolving simulations by combining new algorithms with algorithms already included in SOFA, the modification of most parameters of the simulation (deformable behavior, surface representation, solver, constraints, collision algorithm, etc.) by simply editing an XML file, the building of complex models from simpler ones using a scene-graph description, the efficient simulation of the dynamics of interacting objects using abstract equation solvers, the reuse and easy comparison of a variety of available methods.

- Participants: Christian Duriez, François Faure, Hervé Delingette and Stéphane Cotin
- Partner: IGG
- Contact: Hugo Talbot
- URL: http://www.sofa-framework.org

6.2. SoftRobots

SoftRobots plugin for Sofa

KEYWORDS: Numerical simulations - Problem inverse - Soft robotics

FUNCTIONAL DESCRIPTION: This plugin allows the modeling of deformable robots in the Sofa platform. It allows the modeling of different actuators, such as cable, pneumatic pressure, hydraulics and other simpler types of actuation. It also contains useful tools for animation design or communication with the robot. Coupled with the SoftRobots.Inverse plugin, it also allows the control of these robots. More information can be found on the dedicated website.

- Participants: Christian Duriez, Olivier Goury, Jérémie Dequidt, Damien Marchal, Eulalie Coevoet and Félix Vanneste
- Contact: Christian Duriez
- URL: https://project.inria.fr/softrobot/

6.3. Model Order Reduction Plugin for SOFA

KEYWORDS: Model Order Reduction - Sofa - Finite element modelling

SCIENTIFIC DESCRIPTION: This plugin allows speed-up of SOFA simulations by providing tools to create a reduced version of the SOFA simulation that runs at much higher rates but remains accurate. Starting with a snapshot of the object deformations on a high-dimensional Finite Element mesh, Proper Orthogonal Decomposition (POD) is used to compute a reduced basis of small dimension representing correctly all the possible deformations of the object. The original system describing the object motion is then greatly reduced. To keep numerical efficiency, a hyper-reduction method is used to speed-up the construction of the reduced system.

FUNCTIONAL DESCRIPTION: This plugin allows to dramatically reduce computational time in mechanical simulation in the SOFA framework. A reduced simulation, of much smaller dimension but still accurate is created in an automatic way by the plugin. Building the reduced model may take time, but this operation is made once only. The user can then benefit from a reduced and interactive version of his/her simulation without significant loss of accuracy.

RELEASE FUNCTIONAL DESCRIPTION: This is the first version of the plugin.

NEWS OF THE YEAR: Publication using this plugin accepted dans IEEE Transactions on Robotics

- Participants: Olivier Goury, Félix Vanneste, Christian Duriez and Eulalie Coevoet
- Contact: Olivier Goury
- Publication: Fast, generic and reliable control and simulation of soft robots using model order reduction
- URL: https://project.inria.fr/modelorderreduction/

6.4. SoftRobots.Inverse

KEYWORDS: Sofa - SoftRobots

FUNCTIONAL DESCRIPTION: This plugin builds on the plugin SoftRobots. Inside the plugin, there is some constraint components that are used to describe the robot (effectors, actuators, sensors). An optimisation algorithm is provided to find the efforts to put on actuators in order to place the robot in a the closest possible configuration than the one described by "effectors", or to a state described by "sensors". This method used to control the soft-robots in the task space is patented.

- Partners: CNRS - Université de Lille - Ecole Centrale de Lille
- Contact: Christian Duriez
- URL: https://project.inria.fr/softrobot.inverse

6.5. SofaPython3

KEYWORDS: Python - Numerical simulations - Sofa

FUNCTIONAL DESCRIPTION: This plugin allows to use Sofa as a library from any python3 program. It also allows to write new mechanical component for a Sofa simulation in python3.

- Contact: Christian Duriez
- URL: https://github.com/SofaDefrost/plugin.SofaPython3/

6.6. SofaQtQuick

runSofa2

KEYWORDS: Sofa - GUI (Graphical User Interface) - Modeling - Physical simulation

FUNCTIONAL DESCRIPTION: Smooth the user experience with Sofa By integrating authoring features into runSofa so we can design simulation in an integrated environment. We should be able to model scenes, simulate & debug them.

This tool replaces the old "runSofa" interface, today deprecated but still in use by most SOFA users.

SofaQtQuick provides a fluid and dynamic user experience for SOFA, thanks to the integration of authoring tools to design complex simulations directly in the 3D environment, rather that scripting them as it is done today.

FEATURES:

*Scene graph editing

*Interactive modeling

*Project oriented approach

*Prefab as reusable and parametric object

*2D Canvas

*Custom widgets per component

*Live coding

*Node base interface for data link debugging

*Everything with a non-linear workflow

Based on a code gift from Anatoscope, stringly inspired by Blender & Unity's workflow.

RELEASE FUNCTIONAL DESCRIPTION: 1st Beta version, unstable, but testable.

- Contact: Christian Duriez
- URL: http://github.com/SofaDefrost/SofaQtQuick

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FUN Project-Team

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5. New Software and Platforms

5.1. AspireRFID ALE

FUNCTIONAL DESCRIPTION: AspireRFID middleware is a modular OW2 open source RFID middleware. It is compliant with EPC Global standards. This new module integrates the modifications of the new standard release, including new RP and LLRP definitions and fixing bugs. This module has been implemented in the framework of the MIAOU project.

- Participants: Ibrahim Amadou, Julien Vandaele, Nathalie Mitton and Rim Driss
- Contact: Nathalie Mitton

5.2. ETINODE-CONTIKI-PORT

KEYWORD: Iot

FUNCTIONAL DESCRIPTION: Contiki is an open source embedded OS for Internet of Things (IoT). It is light and portable to different hardware architectures. It embeds communication stacks for IoT. This driver allows the running of Contiki OS over Etinode-MSP430. The code dalso allows the use of radio chip and embedded sensors. This module has been implemented in the framework of the ETIPOPS project.

- Participants: Nathalie Mitton, Roudy Dagher and Salvatore Guzzo Bonifacio
- Contact: Salvatore Guzzo Bonifacio

5.3. ETINODE-DRIVERS

FUNCTIONAL DESCRIPTION: These drivers for Etinode-MSP430 control the different embedded sensors and hardware components available on an Etinode-MSP430 node such as gyroscope, accelerometer and barometric sensor. This module has been implemented in the framework of the ETIPOPS project.

- Participants: Nathalie Mitton, Roudy Dagher and Salvatore Guzzo Bonifacio
- Contact: Salvatore Guzzo Bonifacio

5.4. EVe-TCF

Embedded Verifier for Transitive Control Flow

KEYWORDS: Control Flow - JavaCard - Embedded systems - Embedded - Security - Code analysis

FUNCTIONAL DESCRIPTION: Verification of transitive control flow policies on JavaCard 2.x bytecode. Control flow policies expressed using a DSL language are embedded in JavaCard packages (CAP files) using EVe-TCF convert tool. Control flow policies are then statically verified on-device at loading-time thanks to an embedded verifier (designed for smart cards in EVe-TCF). EVe-TCF (Embedded Verifier for Transitive Control Flow) also contains an off-device (i.e. PC tool) to simulate on-device loading process of JavaCard 2.x platforms with GlobalPlatform 2.x installed.

- Participants: Arnaud Fontaine and Isablle Simplot Ryl
- Contact: Nathalie Mitton

5.5. GOLIATH

Generic Optimized LIghtweight communication stack for Ambient TecHnologies

KEYWORDS: WSN - WSN430

FUNCTIONAL DESCRIPTION: GOLIATH (Generic Optimized LIghtweight communication stack for Ambient TecHnologies) is a full protocol stack for wireless sensor networks. This module has been implemented in the framework of the ETIPOPS project.

- Participants: David Simplot Ryl, Fadila Khadar, Nathalie Mitton and Salvatore Guzzo Bonifacio
- Contact: Nathalie Mitton
- URL: https://gforge.inria.fr/projects/goliath/

5.6. IoT-LAB robots

KEYWORDS: Internet of things - Robotics

FUNCTIONAL DESCRIPTION: IoT-LAB robots is an embedded robot controler on a Turtlebot2 providing the IoT-LAB node mobility functionnality

- Partner: Université de Strasbourg
- Contact: Julien Vandaele
- URL: https://github.com/iot-lab/

5.7. T-SCAN

KEYWORDS: Rfid - RFID Middleware

FUNCTIONAL DESCRIPTION: T-Scan is an interface ensuring the translation from a SGTIN tag format to an ONS hostname format according to the EPCGlobal standards. It allows the sending of a DNS request to look up the EPC-IS aides to which the product belongs in order to access the data relative to that product. This module has been implemented in the framework of the TRACAVERRE project.

- Participants: Gabriele Sabatino and Nathalie Mitton
- Contact: Gabriele Sabatino

5.8. FIT IoT-Lab

Participants: Nathalie Mitton [contact person], Julien Vandaele, Matthieu Berthome.

FIT IoT-LAB (http://www.iot-lab.info) is a very large scale open testbed that features over 2700 wireless sensor nodes and more than 200 robots spread across six different sites in France. Nodes are either fixed or mobile and can be allocated in various topologies throughout all sites. A variety of wireless sensors are available, with different processor architectures (MSP430, STM32 and Cortex-A8) and different wireless chips (802.15.4 PHY at 800 MHz or 2.4 GHz). In addition, "open nodes" can receive custom wireless sensors for inclusion in IoT-LAB testbed. This platform is completely open and can be used by any one wishing to run experiment on wireless sensors and robots.

The Lille site displays 2 subsets of the platforms:

- Haute Borne: this site features 256 M3 sensor nodes operating in the 2.4GHz band and 64 mobile robots (32 turtlebots and 32 wifibots) completely remotely programmable.
- Opennodes: this site features 64 hardware open slots to allow any one to plug his own hardware and benefits from the platform debugging and monitoring tools.

INOCS Project-Team

6. New Software and Platforms

6.1. HappyChic-ApproPick

KEYWORDS: Operational research - Optimization - Java

FUNCTIONAL DESCRIPTION: This software is a prototype developed for the bilateral contract with the company HappyChic. This software is a solver for an integrated warehouse order picking problem with manual picking operations. More precisely, the following problems are solved: (1) the assignment of references to storage positions, based on the iterative solving of minimum cost flow problems, (2) the division of clients orders into several parcels, respecting weight and size constraints, using a dynamic programming algorithm based on the split algorithm, (3) the batching of parcels into trolleys to perform picking tours, using a dynamic programming algorithm based on the split algorithm. The objective function is to minimize the total walking distance. This software is designed to deal with the large-sized industrial instances of HappyChic (considering hundreds of clients, thousands of positions and product references) in a short computation time (few minutes).

- Contact: Maxime Ogier

6.2. KEOLIS-MEDIATOUR

KEYWORDS: Operational research - Mathematical Optimization - Staff scheduling

FUNCTIONAL DESCRIPTION: This software is a prototype developed under a bilateral contract with the company Keolis. This software is a solver which aims to optimize the schedule of mediation staff. More precisely, for each member of the mediation staff working in a public transportation network, MEDIATOUR determines his/her schedule along the day, i.e. when and where he/she is present. Various operational constraints must be taken into account such as the coverage of the network. This software is designed to solve large-scale industrial instances (the subway network of Lille) in short computation times (less than 1 minute).

- Contact: Frederic Semet

6.3. PARROT

Planning Adapter Performing ReRouting and Optimization of Timing

KEYWORDS: Decision aid - Railway - Scheduling

FUNCTIONAL DESCRIPTION: This is a decision support system addressing the problem of the rescheduling railway schedules on the Belgian network when maintenance operations are planned in the short term (2-3 weeks in advance). The deliverable is a software tool that will take as input: (1) the schedules initially planned for the different trains, (2) the initial routes of the trains, (3) maintenance operations / changes of elements in the form of constraints (unavailable routes etc.). It then provides in output: (1) the new train schedule, (2) the new routing of the fleet. The modifications must respect the constraints corresponding to the operations of maintenance. For example, in some cases it is common to leave at least a few minutes interval between two trains using the same track in the station. This constraint must then be propagated if a maintenance operation delays the arrival of a train. New schedules and routings have to be created following a specific goal. Changes made to schedules and routings must minimize: (1) variations on the time spent at the station, (2) the number of partially canceled trains (additional correspondence (s) or stations that are no longer served), (2) the number of fully canceled trains (no stations served).

- Contact: Martine Labbé

LINKS Project-Team

6. New Software and Platforms

6.1. ShEx validator

Validation of Shape Expression schemas

KEYWORDS: Data management - RDF

FUNCTIONAL DESCRIPTION: Shape Expression schemas is a formalism for defining constraints on RDF graphs. This software allows to check whether a graph satisfies a Shape Expressions schema.

RELEASE FUNCTIONAL DESCRIPTION: ShExJava now uses the Commons RDF API and so support RDF4J, Jena, JSON-LD-Java, OWL API and Apache Clerezza. It can parse ShEx schema in the ShExC, ShEJ, ShExR formats and can serialize a schema in ShExJ.

To validate data against a ShExSchema using ShExJava, you have two different algorithms: - the refine algorithm: compute once and for all the typing for the whole graph - the recursive algorithm: compute only the typing required to answer a validate(node,ShapeLabel) call and forget the results.

- Contact: Iovka Boneva
- URL: http://shexjava.lille.inria.fr/

6.2. gMark

gMark: schema-driven graph and query generation

KEYWORDS: Semantic Web - Data base

FUNCTIONAL DESCRIPTION: gMark allow the generation of graph databases and an associated set of query from a schema of the graph.gMark is based on the following principles: - great flexibility in the schema definition - ability to generate big size graphs - ability to generate recursive queries - ability to generate queries with a desired selectivity

- Contact: Aurélien Lemay
- URL: https://github.com/graphMark/gmark

6.3. SmartHal

KEYWORD: Bibliography

FUNCTIONAL DESCRIPTION: SmartHal is a better tool for querying the HAL bibliography database, while is based on Haltool queries. The idea is that a Haltool query returns an XML document that can be queried further. In order to do so, SmartHal provides a new query language. Its queries are conjunctions of Haltool queries (for a list of laboratories or authors) with expressive Boolean queries by which answers of Haltool queries can be refined. These Boolean refinement queries are automatically translated to XQuery and executed by Saxon. A java application for extraction from the command line is available. On top of this, we have build a tool for producing the citation lists for the evaluation report of the LIFL, which can be easily adapter to other Labs.

- Contact: Joachim Niehren
- URL: http://smarthal.lille.inria.fr/

6.4. QuiXPath

KEYWORDS: XML - NoSQL - Data stream

SCIENTIFIC DESCRIPTION: The QuiXPath tools supports a very large fragment of XPath 3.0. The QuiXPath library provides a compiler from QuiXPath to FXP, which is a library for querying XML streams with a fragment of temporal logic.

FUNCTIONAL DESCRIPTION: QuiXPath is a streaming implementation of XPath 3.0. It can query large XML files without loading the entire file in main memory, while selecting nodes as early as possible.

- Contact: Joachim Niehren
- URL: https://project.inria.fr/quix-tool-suite/

6.5. X-FUN

KEYWORDS: Programming language - Compilers - Functional programming - Transformation - XML

FUNCTIONAL DESCRIPTION: X-FUN is a core language for implementing various XML, standards in a uniform manner. X-Fun is a higher-order functional programming language for transforming data trees based on node selection queries.

- Participants: Joachim Niehren and Pavel Labath
- Contact: Joachim Niehren

6.6. ShapeDesigner

KEYWORDS: Validation - Data Exploration - Verification

FUNCTIONAL DESCRIPTION: ShapeDesigner allows construct a ShEx or SHACL schema for an existing dataset. It combines algorithms to analyse the data and automatically extract shape constraints, and to edit and validate shape schemas.

- Contact: Jeremie Dusart
- URL: https://gitlab.inria.fr/jdusart/shexjapp

LOKI Project-Team

6. New Software and Platforms

6.1. Polyphony

KEYWORDS: Human Computer Interaction - Toolkit - Engineering of Interactive Systems

FUNCTIONAL DESCRIPTION: Polyphony is an experimental toolkit demonstrating the use of Entity-Component-System (ECS) to design Graphical User Interfaces (GUI). It also extends the original ECS model to support advanced interfaces.

NEWS OF THE YEAR: Design and implementation of a first version of the toolkit and associated examples as a proof of concept.
- Participants: Thibault Raffaillac and Stéphane Huot
- Contact: Stéphane Huot
- Publications: Applying the Entity-Component-System Model to Interaction Programming - Polyphony: Programming Interfaces and Interactions with the Entity-Component-System Model
- URL: https://gitlab.inria.fr/Loki/PolyphonyECS

6.2. Esquisse

KEYWORDS: Vector graphics - 3D interaction - Human Computer Interaction

SCIENTIFIC DESCRIPTION: Trace figures are contour drawings of people and objects that capture the essence of scenes without the visual noise of photos or other visual representations. Their focus and clarity make them ideal representations to illustrate designs or interaction techniques. In practice, creating those figures is a tedious task requiring advanced skills, even when creating the figures by tracing outlines based on photos. To mediate the process of creating trace figures, we introduce the open-source tool Esquisse. Informed by our taxonomy of 124 trace figures, Esquisse provides an innovative 3D model staging workflow, with specific interaction techniques that facilitate 3D staging through kinematic manipulation, anchor points and posture tracking. Our rendering algorithm (including stroboscopic rendering effects) creates vector-based trace figures of 3D scenes. We validated Esquisse with an experiment where participants created trace figures illustrating interaction techniques, and results show that participants quickly managed to use and appropriate the tool.

FUNCTIONAL DESCRIPTION: Esquisse is an add-on for Blender that can be used to rapidly produce trace figures. It relies on a 3D model staging workflow, with specific interaction techniques that facilitate the staging through kinematic manipulation, anchor points and posture tracking. Staged 3D scenes can be exported to SVG thanks to Esquisse's dedicated rendering algorithm.

NEWS OF THE YEAR: First version of Esquisse, implementing both staging and vector rendering.
- Contact: Sylvain Malacria
- Publication: Esquisse: Using 3D Models Staging to Facilitate the Creation of Vector-based Trace Figures
- URL: https://github.com/LokiResearch/Esquisse

6.3. RayCursor

Source code for the pointing technique RayCursor

KEYWORDS: Virtual reality - Interaction technique

FUNCTIONAL DESCRIPTION: This is a Unity Project containing the source code and prefab for the pointing technique RayCursor to be easily integrated in other Unity Projects.
- Contact: Géry Casiez
- Publications: RayCursor: a 3D Pointing Facilitation Technique based on Raycasting - Improving Raycasting using Proximity Selection and Filtering
- URL: http://ns.inria.fr/loki/raycursor/

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MAGNET Project-Team

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6. New Software and Platforms

6.1. CoRTeX

Python library for noun phrase COreference Resolution in natural language TEXts

KEYWORD: Natural language processing

FUNCTIONAL DESCRIPTION: CoRTex is a LGPL-licensed Python library for Noun Phrase coreference resolution in natural language texts. This library contains implementations of various state-of-the-art coreference resolution algorithms, including those developed in our research. In addition, it provides a set of APIs and utilities for text pre-processing, reading the CONLL2012 and CONLLU annotation formats, and performing evaluation, notably based on the main evaluation metrics (MUC, B-CUBED, and CEAF). As such, CoRTex provides benchmarks for researchers working on coreference resolution, but it is also of interest for developers who want to integrate a coreference resolution within a larger platform. It currently supports use of the English or French language.

- Participant: Pascal Denis
- Partner: Orange Labs
- Contact: Pascal Denis
- URL: https://gitlab.inria.fr/magnet/CoRTeX

6.2. Mangoes

MAgnet liNGuistic wOrd vEctorS

KEYWORDS: Word embeddings - NLP

FUNCTIONAL DESCRIPTION: Process textual data and compute vocabularies and co-occurrence matrices. Input data should be raw text or annotated text. Compute word embeddings with different state-of-the art unsupervised methods. Propose statistical and intrinsic evaluation methods, as well as some visualization tools.

- Contact: Nathalie Vauquier
- URL: https://gitlab.inria.fr/magnet/mangoes

6.3. metric-learn

KEYWORDS: Machine learning - Python - Metric learning

FUNCTIONAL DESCRIPTION: Distance metrics are widely used in the machine learning literature. Traditionally, practicioners would choose a standard distance metric (Euclidean, City-Block, Cosine, etc.) using a priori knowledge of the domain. Distance metric learning (or simply, metric learning) is the sub-field of machine learning dedicated to automatically constructing optimal distance metrics.

This package contains efficient Python implementations of several popular metric learning algorithms.

- Partner: Parietal
- Contact: Aurélien Bellet
- URL: https://github.com/scikit-learn-contrib/metric-learn

6.4. MyLocalInfo

KEYWORDS: Privacy - Machine learning - Statistics

FUNCTIONAL DESCRIPTION: Decentralized algorithms for machine learning and inference tasks which (1) perform as much computation as possible locally and (2) ensure privacy and security by avoiding personal data leaves devices.

- Contact: Nathalie Vauquier
- URL: https://gitlab.inria.fr/magnet/mylocalinfo

MEPHYSTO Team (section vide)

MODAL Project-Team

6. New Software and Platforms

6.1. MixtComp

Mixture Computation

KEYWORDS: Clustering - Statistics - Missing data

FUNCTIONAL DESCRIPTION: MixtComp (Mixture Computation) is a model-based clustering package for mixed data originating from the Modal team (Inria Lille). It has been engineered around the idea of easy and quick integration of all new univariate models, under the conditional independence assumption. New models will eventually be available from researches, carried out by the Modal team or by other teams. Currently, central architecture of MixtComp is built and functionality has been field-tested through industry partnerships. Three basic models (Gaussian, multinomial, Poisson) are implemented, as well as two advanced models (Ordinal and Rank). MixtComp has the ability to natively manage missing data (completely or by interval). MixtComp is used as an R package, but its internals are coded in C++ using state of the art libraries for faster computation.

- Participants: Christophe Biernacki, Etienne Goffinet, Matthieu Marbac-Lourdelle, Quentin Grimonprez, Serge Iovleff and Vincent Kubicki
- Contact: Christophe Biernacki
- URL: https://cran.r-project.org/web/packages/RMixtComp/index.html

6.2. BlockCluster

Block Clustering

KEYWORDS: Statistic analysis - Clustering package

SCIENTIFIC DESCRIPTION: Simultaneous clustering of rows and columns, usually designated by biclustering, co-clustering or block clustering, is an important technique in two way data analysis. It consists of estimating a mixture model which takes into account the block clustering problem on both the individual and variables sets. The blockcluster package provides a bridge between the C++ core library and the R statistical computing environment. This package allows to co-cluster binary, contingency, continuous and categorical data-sets. It also provides utility functions to visualize the results. This package may be useful for various applications in fields of Data mining, Information retrieval, Biology, computer vision and many more.

FUNCTIONAL DESCRIPTION: BlockCluster is an R package for co-clustering of binary, contingency and continuous data based on mixture models.

RELEASE FUNCTIONAL DESCRIPTION: Initialization strategy enhanced

- Participants: Christophe Biernacki, Gilles Celeux, Parmeet Bhatia, Serge Iovleff, Vincent Brault and Vincent Kubicki
- Partner: Université de Technologie de Compiègne
- Contact: Serge Iovleff
- URL: http://cran.r-project.org/web/packages/blockcluster/index.html

6.3. CloHe

Clustering of Mixed data

KEYWORDS: Classification - Clustering - Missing data

FUNCTIONAL DESCRIPTION: Software of classification for mixed data with missing values with application to multispectral satellite image time-series

- Partners: CNRS - INRA
- Contact: Serge Iovleff
- URL: https://modal.lille.inria.fr/CloHe/

6.4. PACBayesianNMF

KEYWORDS: Statistics - Machine learning

FUNCTIONAL DESCRIPTION: Implementing NMF with a PAC-Bayesian approach relying upon block gradient descent

- Participants: Benjamin Guedj and Astha Gupta
- Contact: Benjamin Guedj
- URL: https://github.com/astha736/PACbayesianNMF

6.5. pycobra

KEYWORDS: Statistics - Data visualization - Machine learning

SCIENTIFIC DESCRIPTION: pycobra is a python library for ensemble learning, which serves as a toolkit for regression, classification, and visualisation. It is scikit-learn compatible and fits into the existing scikit-learn ecosystem.

pycobra offers a python implementation of the COBRA algorithm introduced by Biau et al. (2016) for regression.

Another algorithm implemented is the EWA (Exponentially Weighted Aggregate) aggregation technique (among several other references, you can check the paper by Dalalyan and Tsybakov (2007).

Apart from these two regression aggregation algorithms, pycobra implements a version of COBRA for classification. This procedure has been introduced by Mojirsheibani (1999).

pycobra also offers various visualisation and diagnostic methods built on top of matplotlib which lets the user analyse and compare different regression machines with COBRA. The Visualisation class also lets you use some of the tools (such as Voronoi Tesselations) on other visualisation problems, such as clustering.

- Participants: Bhargav Srinivasa Desikan and Benjamin Guedj
- Contact: Benjamin Guedj
- Publication: Pycobra: A Python Toolbox for Ensemble Learning and Visualisation
- URL: https://github.com/bhargavvader/pycobra

6.6. STK++

Statistical ToolKit

KEYWORDS: Statistics - Linear algebra - Framework - Learning - Statistical learning

FUNCTIONAL DESCRIPTION: STK++ (Statistical ToolKit in C++) is a versatile, fast, reliable and elegant collection of C++ classes for statistics, clustering, linear algebra, arrays (with an API Eigen-like), regression, dimension reduction, etc. The library is interfaced with lapack for many linear algebra usual methods. Some functionalities provided by the library are available in the R environment using rtkpp and rtkore.

STK++ is suitable for projects ranging from small one-off projects to complete data mining application suites.

- Participant: Serge Iovleff
- Contact: Serge Iovleff
- URL: http://www.stkpp.org

6.7. rtkore

STK++ core library integration to R using Rcpp

KEYWORDS: C++ - Data mining - Clustering - Statistics - Regression

FUNCTIONAL DESCRIPTION: STK++ (http://www.stkpp.org) is a collection of C++ classes for statistics, clustering, linear algebra, arrays (with an Eigen-like API), regression, dimension reduction, etc. The integration of the library to R is using Rcpp. The rtkore package includes the header files from the STK++ core library. All files contain only templated classes or inlined functions. STK++ is licensed under the GNU LGPL version 2 or later. rtkore (the stkpp integration into R) is licensed under the GNU GPL version 2 or later. See file LICENSE.note for details.

- Participant: Serge Iovleff
- Contact: Serge Iovleff
- URL: https://cran.r-project.org/web/packages/rtkore/index.html

6.8. MixAll

Clustering using Mixture Models

KEYWORDS: Clustering - Clustering package - Generative Models

FUNCTIONAL DESCRIPTION: MixAll is a model-based clustering package for modelling mixed data sets. It has been engineered around the idea of easy and quick integration of any kind of mixture models for any kind of data, under the conditional independence assumption. Currently five models (Gaussian mixtures, categorical mixtures, Poisson mixtures, Gamma mixtures and kernel mixtures) are implemented. MixAll has the ability to natively manage completely missing values when assumed as random. MixAll is used as an R package, but its internals are coded in C++ as part of the STK++ library (www.stkpp.org) for faster computation.

RELEASE FUNCTIONAL DESCRIPTION: clusterPredict allow to predcit membership for a new data set using a previously estimated model

- Participant: Serge Iovleff
- Partner: Université Lille 1
- Contact: Serge Iovleff
- URL: https://cran.r-project.org/web/packages/MixAll/

6.9. simerge

Statistical Inference for the Management of Extrem Risks, Genetics and Global epidemiology

KEYWORD: Biclustering

FUNCTIONAL DESCRIPTION: Allows to perform Co-Clustering on binary (Bernoulli) and counting variables (Poisson) using co-variables.

- Partner: Inria
- Contact: Serge Iovleff

6.10. MixtComp.V4

KEYWORDS: Clustering - Statistics - Missing data - Mixed data

FUNCTIONAL DESCRIPTION: MixtComp (Mixture Computation) is a model-based clustering package for mixed data originating from the Modal team (Inria Lille). It has been engineered around the idea of easy and quick integration of all new univariate models, under the conditional independence assumption. New models will eventually be available from researches, carried out by the Modal team or by other teams. Currently, central architecture of MixtComp is built and functionality has been field-tested through industry partnerships. Five basic models (Gaussian, Multinomial, Poisson, Weibull, NegativeBinomial) are implemented, as well as two advanced models (Functional and Rank). MixtComp has the ability to natively manage missing data (completely or by interval). MixtComp is used as an R package, but its internals are coded in C++ using state of the art libraries for faster computation.

RELEASE FUNCTIONAL DESCRIPTION: - New I/O system - Replacement of regex library - Improvement of initialization - Criteria for stopping the algorithm - Added management of partially missing data for several models - User documentation - Adding user features in R

- Participants: Christophe Biernacki, Vincent Kubicki, Matthieu Marbac-Lourdelle, Serge Iovleff, Quentin Grimonprez and Etienne Goffinet
- Partners: Université de Lille - CNRS
- Contact: Christophe Biernacki

6.11. MASSICCC

Massive Clustering with Cloud Computing

KEYWORDS: Statistic analysis - Big data - Machine learning - Web Application

SCIENTIFIC DESCRIPTION: The web application let users use several software packages developed by Inria directly in a web browser. Mixmod is a classification library for continuous and categorical data. MixtComp allows for missing data and a larger choice of data types. BlockCluster is a library for co-clustering of data. When using the web application, the user can first upload a data set, then configure a job using one of the libraries mentioned and start the execution of the job on a cluster. The results are then displayed directly in the browser allowing for rapid understanding and interactive visualisation.

FUNCTIONAL DESCRIPTION: The MASSICCC web application offers a simple and dynamic interface for analysing heterogeneous data with a web browser. Various software packages for statistical analysis are available (Mixmod, MixtComp, BlockCluster) which allow for supervised and supervised classification of large data sets.

- Contact: Christophe Biernacki
- URL: https://massiccc.lille.inria.fr

6.12. Platforms

6.12.1. MASSICCC Platform

MASSICCC is a demonstration platform giving access through a SaaS (service as a software) concept to data analysis libraries developed at Inria. It allows obtaining results either directly through a website specific display (specific and interactive visual outputs) or through an R data object download. It started in October 2015 for two years and is common to the Modal team (Inria Lille) and the Select team (Inria Saclay). In 2016, two packages have been integrated: Mixmod and MixtComp (see the specific section about MixtComp). In 2017, the BlockCluster package has been integrated and also a particular attention to provide meaningful graphical outputs (for Mixmod, MixtComp and BlockCluster) directly in the web platform itself has led to some specific developments. In 2019, a new version of the MixtComp software has been developed.

<p style="text-align:center">**RAPSODI Project-Team**</p>

6. New Software and Platforms

6.1. Platforms

6.1.1. Platform NS2DDV-M

`NS2DDV-M` [42] is a Matlab code, developed by C. Calgaro, E. Creusé, and A. Mouton (CNRS research engineer at Université de Lille), for the simulation of homogeneous and inhomogeneous fluid flows by a combined Finite Volume-Finite Element method. The code embeds parallel computation facilities, and is freely distributed, to allow for easy comparisons with concurrent codes on benchmark test-cases, and to promote new collaborations in the domain.

6.1.2. Platform KinDiff

`KinDiff` consists in a Python library and a Jupyter Notebook. It has been developed by M. Bessemoulin-Chatard (CNRS and Université de Nantes), M. Herda, and T. Rey. The `KinDiff` code approximates the solutions to the kinetic Fokker–Planck and linear BGK equations in a unidimensional periodic domain in space and a symmetric bounded unidimensional domain in velocity. Its outputs are the discretization of the distribution function in the phase space as well as the moments, along with some visualizations of these quantities. Kinetic equations display asymptotic behaviors such as return to equilibrium in large time, or convergence towards macroscopic equations in the diffusive limit. The finite volume method implemented within `KinDiff` reproduces these asymptotics at the discrete level. The presentation and numerical analysis of the scheme is available in the article [17]. The code is available at gitlab.com/thoma.rey/FV_HipoDiff.

<p style="text-align:center">**RMOD Project-Team**</p>

6. New Software and Platforms

6.1. Moose

Moose: Software and Data Analysis Platform

KEYWORDS: Software engineering - Meta model - Software visualisation

FUNCTIONAL DESCRIPTION: Moose is an extensive platform for software and data analysis. It offers multiple services ranging from importing and parsing data, to modeling, to measuring, querying, mining, and to building interactive and visual analysis tools. The development of Moose has been evaluated to 200 man/year.

Mots-cles : MetaModeling, Program Visualization, Software metrics, Code Duplication, Software analyses, Parsers

- Participants: Anne Etien, Nicolas Anquetil, Olivier Auverlot, Stéphane Ducasse, Julien Delplanque, Guillaume Larcheveque, Cyril Ferlicot-Delbecque and Pavel Krivanek
- Partners: Université de Berne - Sensus - Synectique - Pleiad - USI - Vrije Universiteit Brussel
- Contact: Stéphane Ducasse
- URL: http://www.moosetechnology.org

6.2. Pharo

KEYWORDS: Live programmation objet - Reflective system - Web Application

FUNCTIONAL DESCRIPTION: Pharo is a pure object reflective and dynamic language inspired by Smalltalk. In addition, Pharo comes with a full advanced programming environment developed under the MIT License. It provides a platform for innovative development both in industry and research. By providing a stable and small core system, excellent developer tools, and maintained releases, Pharo's goal is to be a platform to build and deploy mission critical applications, while at the same time continue to evolve. Pharo 60 got 100 contributors world-wide. It is used by around 30 universities, 15 research groups and around 40 companies.

- Participants: Christophe Demarey, Clement Bera, Damien Pollet, Esteban Lorenzano, Marcus Denker, Stéphane Ducasse and Guillermo Polito
- Partners: BetaNine - Reveal - Inceptive - Netstyle - Feenk - ObjectProfile - GemTalk Systems - Greyc Université de Caen - Basse-Normandie - Université de Berne - Yesplan - RMod - Pleiad - Sensus - Université de Bretagne Occidentale - École des Mines de Douai - ENSTA - Uqbar foundation Argentina - LAM Research - ZWEIDENKER - LifeWare - JPMorgan Chase - KnowRoaming - ENIT - Spesenfuchs - FINWorks - Esug - FAST - Ingenieubüro Schmidt - Projector Software - HRWorks - Inspired.org - Palantir Solutions - High Octane - Soops - Osoco - Ta Mère SCRL - University of Yaounde 1 - Software Quality Laboratory, University of Novi Sad - Software Institute Università della Svizzera italiana - Universdad Nacional de Quilmes - UMMISCO IRD - Université technique de Prague
- Contact: Marcus Denker
- URL: http://www.pharo.org

6.3. Pillar

KEYWORDS: HTML - LaTeX - HTML5

FUNCTIONAL DESCRIPTION: Pillar is a markup syntax and associated tools to write and generate documentation and books. Pillar is currently used to write several books and other documentation. It is used in the tools developed by Feenk.com.

- Partner: Feenk
- Contact: Stéphane Ducasse
- URL: https://github.com/Pillar-markup/pillar

SEQUEL Project-Team

6. New Software and Platforms

6.1. gym-backgammon

Backgammon environment

KEYWORD: Artificial intelligence

FUNCTIONAL DESCRIPTION: This software program follows the openai gym API (https://gym.openai.com/), that is the interaction loop of reinforcement learning: the game is in a certain state, the agent selects an action, this action is simulated in the game, and the next state of the game as well as the return are returned to the agent. All these notions follows backgammon rules and should be understood as pertaining to the reinforcement learning vocabulary. As far as we are aware of, gym-backgammon is the only existing software of this type, and it is available in open source. Great care has been put into the debugging and the efficiency. This software program is developped in python. The inetraction is made according to a client-server model.

- Author: Alessio Della Libera
- Contact: Philippe Preux
- URL: https://github.com/dellalibera/gym-backgammon

6.2. gym-rubik

Rubik's cube environment

KEYWORD: Artificial intelligence

FUNCTIONAL DESCRIPTION: This software program follows the openai gym API (https://gym.openai.com/), that is the interaction loop of reinforcement learning: the game is in a certain state, the agent selects an action, this action is simulated in the game, and the next state of the game as well as the return are returned to the agent. All these notions follows Rubik's cube rules and should be understood as pertaining to the reinforcement learning vocabulary. Great care has been put into the debugging and the efficiency. This software program is developped in python.

- Author: Raphaël Avalos Martinez De Escobar
- Contact: Philippe Preux
- URL: https://github.com/raphaelavalos/gym-rubikscube

6.3. highway-env

An environment for autonomous driving decision-making

KEYWORDS: Generic modeling environment - Simulation - Autonomous Cars - Artificial intelligence

FUNCTIONAL DESCRIPTION: The environment is composed of several variants, each of which corresponds to driving scenes: highway, roundabout, intersection, merge, parking, etc. The road network is described by a graph, and is then populated with simulated vehicles. Vehicle kinematics follows a simple Bicycle model, and their behavior is determined by models derived from road traffic simulation literature. The ego-vehicle has access to a description of the scene through several types of observations, and its behavior is controlled through an action space, either discrete (change of lanes, of cruising speed) or continuous (accelerator pedal, steering wheel angle). The objective function to maximize is also described by the environment and may vary depending on the task to be solved. The interface of the library is inherited from the standard defined by OpenAI Gym, consisting of four main methods: gym.make(id), env.step(action), env.reset(), and env.render().

- Author: Edouard Leurent
- Contact: Edouard Leurent

SPIRALS Project-Team

6. New Software and Platforms

6.1. APISENSE

KEYWORDS: Mobile sensing - Crowd-sensing - Mobile application - Crowd-sourcing - Android

FUNCTIONAL DESCRIPTION: APISENSE platform is a software solution to collect various contextual information from Android devices (client application) and automatically upload collected data to a server (deployed as a SaaS). APISENSE is based on a Cloud computing infrastructure to facilitate datasets collection from significant populations of mobile users for research purposes.

- Participants: Antoine Veuiller, Christophe Ribeiro, Julien Duribreux, Nicolas Haderer, Romain Rouvoy, Romain Sommerard and Lakhdar Meftah
- Partner: Université de Lille
- Contact: Romain Rouvoy
- URL: https://apisense.io

6.2. PowerAPI

KEYWORDS: Energy efficiency - Energy management

FUNCTIONAL DESCRIPTION: PowerAPI is a library for monitoring the energy consumption of software systems.

PowerAPI differs from existing energy process-level monitoring tool in its software orientation, with a fully customizable and modular solution that let the user to precisely define what he/she wants to monitor. PowerAPI is based on a modular and asynchronous event-driven architecture using the Akka library. PowerAPI offers an API which can be used to define requests about energy spent by a process, following its hardware resource utilization (in term of CPU, memory, disk, network, etc.).

- Participants: Adel Noureddine, Loïc Huertas, Maxime Colmant, Romain Rouvoy, Mohammed Chakib Belgaid and Arthur D'azemar
- Contact: Romain Rouvoy
- URL: http://powerapi.org

6.3. Saloon

KEYWORDS: Feature Model - Software Product Line - Cloud computing - Model-driven engineering - Ontologies

FUNCTIONAL DESCRIPTION: Saloon is a framework for the selection and configuration of Cloud providers according to application requirements. The framework enables the specification of such requirements by defining ontologies. Each ontology provides a unified vision of provider offers in terms of frameworks, databases, languages, application servers and computational resources (i.e., memory, storage and CPU frequency). Furthermore, each provider is related to a Feature Model (FM) with attributes and cardinalities, which captures its capabilities. By combining the ontology and FMs, the framework is able to match application requirements with provider capabilities and select a suitable one. Specific scripts to the selected provider are generated in order to enable its configuration.

- Participants: Clément Quinton, Daniel Romero Acero, Laurence Duchien, Lionel Seinturier and Romain Rouvoy
- Partner: Université de Lille
- Contact: Clément Quinton
- URL: https://gitlab.irisa.fr/drome00A/saloon

6.4. SPOON

KEYWORDS: Java - Code analysis

FUNCTIONAL DESCRIPTION: Spoon is an open-source library that enables you to transform (see below) and analyze Java source code (see example). Spoon provides a complete and fine-grained Java metamodel where any program element (classes, methods, fields, statements, expressions...) can be accessed both for reading and modification. Spoon takes as input source code and produces transformed source code ready to be compiled.

- Participants: Gérard Paligot, Lionel Seinturier, Martin Monperrus, Nicolas Petitprez and Simon Urli
- Contact: Martin Monperrus
- URL: http://spoon.gforge.inria.fr

VALSE Project-Team

6. New Software and Platforms

6.1. Platforms

6.1.1. ControlHub

ControlHub is the platform for the rapid prototyping of control algorithms of cyber-physical systems. It allows the End-User to have a remote access to real experimental setups in order to validate mathematical control and estimation algorithms.